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(2.1) $R = \text{rot}(\hat{Y}, \varphi) \text{rot}(\hat{Z}, \theta) \ c\varphi \ 0 \ s\varphi = 0 \ 1 \ 0 \ -s\varphi \ 0 \ \dots$

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Laws of Robotics • Asimov proposed three “Laws of Robotics” and later added the “zeroth law” • Law 0: A robot may not injure

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humanity or through inaction, allow humanity to come to harm •
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